

Partial orders in tame ordered structures

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Question

- J. Truss asked whether any definable partial order in an o-minimal structure could be definably extended to a linear order.
- We will positively answer a generalization of this question, by describing several classes of ordered structures that definably extend their definable partial orders.
- These structures can be thought of as possessing a “definable” order extension principle – in these structures, the “order extension principle” of ZFC holds definably. Formally:

Definition

Let M be a structure. Say that M has the order extension principle (has OE) if, for any M -definable partial order (P, \prec) , there is an M -definable linear order \prec' that totally orders P and such that $x \prec y \Rightarrow x \prec' y$.

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Examples of structures with OE

A structure M has OE if it definably extends any partial order to a total one.

In this talk, we will prove that the following structures have OE:

- 1 All well-ordered structures.
 - 2 All (weakly) o-minimal structures (every definable 1-dimensional set is a finite union of points and convex sets).
 - 3 All (weakly-)quasi-o-minimal structures.
- Prior to our work, the only results in this direction were when the partial order was 1-dimensional (just a subset of M).
 - MacPherson and Steinhorn did the case when M was o-minimal.
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The key easy step

- Our work hinges on an easy observation: that any family of sets induces a partial order on its parameter set.
- Let $\mathcal{V} = \{V(x) : x \in A\}$ be any family of sets, parameterized by A .
- Let $\prec_{\mathcal{V}}$ be the partial order on A given by the relation $x \prec_{\mathcal{V}} y$ if and only if $V(x) \subsetneq V(y)$.

Definition

Let (P, \prec) be a partial order. Let $L(x) = \{y \in P : y \prec x\}$ for $x \in P$ – the “lower cone” of x .

- Let $\mathcal{V} = \{L(x) : x \in P\}$. Then $\prec_{\mathcal{V}}$ is a partial order on P .
- Note that if $x \prec y$, then by transitivity and the fact that $x \in L(y) \setminus L(x)$, we have $x \prec_{\mathcal{V}} y$, so $\prec_{\mathcal{V}}$ is a partial order on P extending \prec .
- Thus, if we can linearly extend the partial order $\prec_{\mathcal{V}}$ for any definable family \mathcal{V} , we can linearly extend any partial order.

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Well-ordered structures

To show M has OE, we need to show that if A is the parameter set of a definable family of sets \mathcal{V} , then A can be linearly ordered, compatible with $\prec_{\mathcal{V}}$.

Theorem

Let M be a well-ordered structure. Then M has OE.

- Let A be the parameter set for $\mathcal{V} = \{V(x) : x \in A\}$, a definable family of sets in M^n for some $n \geq 0$. We consider the case $n = 1$. The general case is similar.
- For $x, y \in A$, let $B(x, y) = V(x) \triangle V(y)$. Since M is well-ordered, there is a least element of $B(x, y)$. Then for $x, y \in A$, let $x \prec y$ if $t \in V(y)$ (so $t \notin V(x)$).
- If x and y are still unordered, then $V(x) = V(y)$. Order x and y lexicographically.

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- For $t \in M$ and any set $X \subseteq M^n$, let $X_t = \{y : \langle t, y \rangle \in X\}$, the fiber of X over t .
- For higher dimensions, we use the fact that for any $t \in M$, we can consider the family $\mathcal{V}_t = \{V(x)_t : x \in A\}$.
- This induces a partial order \prec_t on A .
- The collection \mathcal{V}_t is a family of $(n - 1)$ -dimensional sets and so, by induction, we may extend each \prec_t to a linear order on A , uniformly in t .
- Instead of letting $B(x, y) = V(x) \Delta V(y)$, we set $B(x, y) = \{t : V(x)_t \neq V(y)_t\}$. Then we let $x \prec y$ if $x \prec_t y$ for t the least element of $B(x, y)$.

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The general case

The previous proof gives the principle for subsequent proofs: if there is some consistent way to pick out a particular part of $B(x, y)$, for which each \prec_t gives the same answer about x and y , then we can use that answer to order x and y .

Theorem (R., Steinhorn)

Let M be an ordered structure such that, for any definable $A, C \subseteq M$, there is some initial segment of A either contained in or disjoint from C . Then M has OE.

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Let M be an ordered structure such that, for any definable $A, C \subseteq M$, there is some initial segment of A either contained in or disjoint from C . Then M has OE.

Theorem: Any ordered structure with tame initial segment behavior of definable sets has OE.

Proof.

- As before, we restrict to the 1-dimensional case for simplicity.
- The proof proceeds as in the well-ordered case until we have $B(x, y) = V(x) \triangle V(y)$.
- Consider the definable set $\{t : t \in V(y) \setminus V(x)\}$. By hypothesis, this set either contains or is disjoint from an initial segment of $B(x, y)$.
- If it contains an initial segment of $B(x, y)$, then set $x \prec y$.
Otherwise, let $y \prec x$.
- It is then routine to verify that this yields a nearly-total order, which is completed lexicographically.



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If M is an ordered structure such that for any definable $A, C \subseteq M$, C contains or is disjoint from an initial segment of A , then M has OE.

- The theorem immediately implies our results on well-ordered, o-minimal, and weakly o-minimal structures.
- Note that while the hypothesis on M in the theorem is first-order, the properties of being well-ordered or weakly o-minimal are not first-order.
- Thus, if *some* model of the theory of M is weakly o-minimal or well-ordered, then M satisfies the requisite hypothesis.

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Theorem

If M is an ordered structure such that for any definable $A, C \subseteq M$, C contains or is disjoint from an initial segment of A , then M has OE.

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- As referred to before, if there is some consistent way to pick out a particular part of $B(x, y)$, for which each \prec_t gives the same answer about x and y , then we can use that answer to order x and y .
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Recall that a structure is ω -saturated if any type over finitely many element is realized in the structure itself.

Definition

Say that an ω -saturated ordered structure M has (\ddagger) if for any complete type $p \in S_1(\emptyset)$ and any definable sets $A, C \subseteq M$, the set $p(M) \cap A$ has an initial segment either disjoint from or contained in C .

- This is a natural generalization of the previous property we looked at.
- Instead of looking at the whole structure when we intersect sets, we restrict to a \emptyset -definable type.
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(\ddagger): inside a type over the empty set, initial segments of definable sets are tame

Lemma

If M has (\ddagger), then, given A and C , we may actually replace the type p in the statement of (\ddagger) by some formula $\varphi \in p$. Thus some initial segment of $\varphi(M) \cap A$ is contained in or disjoint from C . Moreover, φ is independent of the parameters used to define A, C .

The lemma comes from a straightforward use of compactness, and allows us to replace types by formulas.

Theorem (R., Steinhorn)

Let M be an ω -saturated ordered structure with (\ddagger). Then M has OE.

The proof proceeds as before, but the definition of the order in terms of $B(x, y)$ will be considerably more complicated, due to multiple applications of compactness.

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Theorem: Let M be an ω -saturated ordered structure with tame initial segment behavior inside types over \emptyset . Then M has OE.

- Let $x, y \in A$. As before, we consider the one-dimensional case.
- We want to look at $V(y) \setminus V(x)$ on an “initial segment” of $B(x, y)$.
- However, the set $V(y) \setminus V(x)$ may not behave nicely on an initial segment of $B(x, y)$, so we must consider it on types near the lower boundary of $B(x, y)$.
- Let $C(x, y)$ be the upward closure of $B(x, y)$.
- Let P be the set of all types over \emptyset that have realizations coinital in $C(x, y)$.
- For each type $p \in P$, there is some formula φ_p such that for t in an initial segment of $\varphi_p(M) \cap C(x, y)$, the statements $t \in V(x)$ and $t \in V(y)$ have constant truth value.
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- For this p , we know that on an initial segment of φ_p , we have (without loss of generality) $t \in V(y) \setminus V(x)$.
- Since there are such p and φ_p for every choice of x', y' such that $C(x', y') = C(x, y)$, there must be finitely many choices for φ_p .
- Applying compactness again, this time allowing x and y to vary so that $C(x, y)$ changes, we obtain finitely many formulas $\varphi_1, \dots, \varphi_m$ such that for any $x, y \in A$ and each $i \leq m$, either:
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- Now we can set $x \prec y$ if and only if on the first $i \leq m$ such that (2) fails, we have $t \in V(y) \setminus V(x)$ on an initial segment of $\varphi_i(M) \cap C(x, y)$.
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- We can also weaken “interval” to “convex set,” obtaining weakly-quasi-o-minimal structures.
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